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# HRW

## High Resolution Winds

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# Summary

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HRW product content.

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Some known problems.

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# HRW product content

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In form of **BUFR bulletins** (observations like):

- **Basic data:**

**Latitudes and longitudes** ( at  $t-\Delta t$  slot, increment  $t-\Delta t$  to  $t$ ).

**Temperature (K) and pressure level (hPa)** for the tracer.

**Wind direction (degrees) and speed (mps).**

**Quality indicator (QI, %).**

- **Additional data:**

Time increment ( $\Delta t$ ).

Tracer size (= best average resolution) (km).

Recommended quality threshold (set to 60%).

Processing indicators (tracer, tracking, level, guess, q.c. steps) (\*).

# Algorithms overview

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## Steps:

Image pre-processing.

Tracers.

Guess (NWP)(\*).

Level assignment.

Tracking.

Flagging.

And Selection.

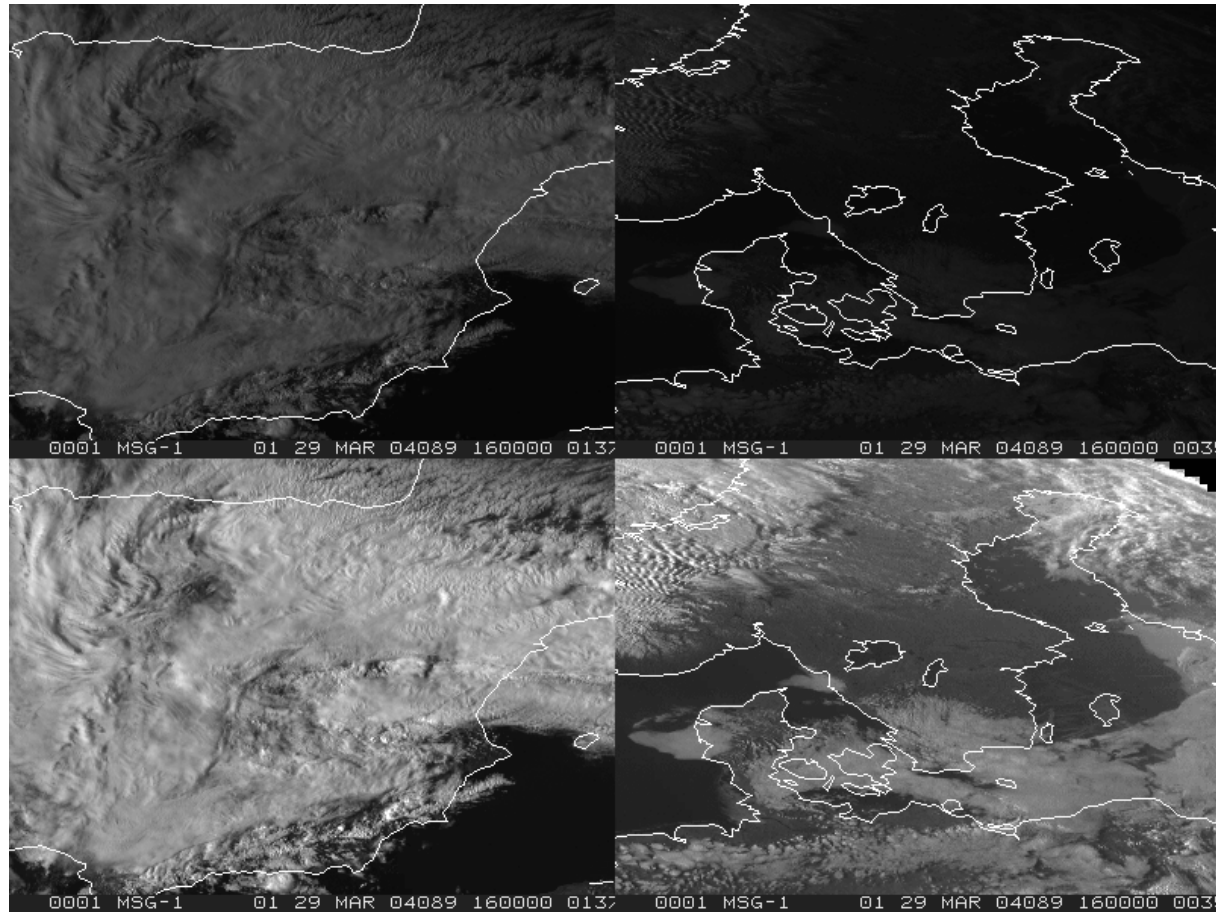
# Algorithms: Image pre-processing

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- A Region of the HRV channel is processed (\*).  
*(channel most indicated to nowcasting applications).*
- Raw data are "normalised" ( division by  $\cos-z$ ,  $z$  is the sun- zenith angle).  
*(allow using fixed threshold value).*
- Range of brightness reduced to values in range 0-255 (8 bits).  
*(MOP/MTP heritage, but also because quite low contrasts not much desired at tracking).*

# Algorithms: Image pre-processing

HRV brightness



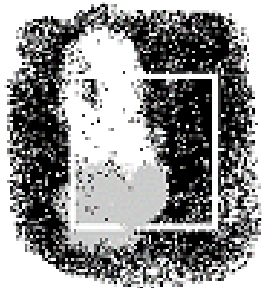
# Algorithms: Tracers

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## 2 methods:

- **Gradient:** search of well defined cloud edges.  
*(well proven, good, fast).*
- **Tracer characteristics:** to fill "holes" in coverage.  
Around each "candidate tracer" location, checks for:
  - A threshold clearly separating "bright" vs. "no bright" pixels.  
*(the cloudiness or clear part of it, in front of a "background").*
  - A rough distribution of "bright" pixels showing a "well defined" shape.  
*(e.g. avoid "too linear" cloudy elements).*
  - And not much scatter in IR-channel temperatures for "bright".  
*(avoid multilevel cloudiness) (\*\*).*

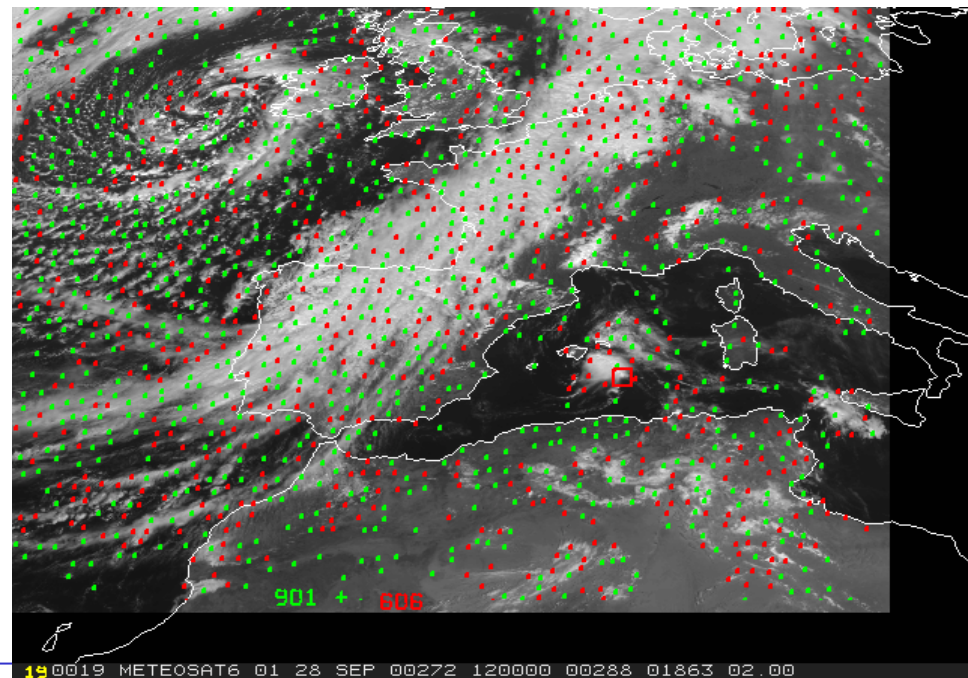
# Algorithms: Tracers



2 2 0 0	2 2 0 0
2 2 1 0	2 2 1 0
2 2 1 0	1 1 0 0
2 2 1 0	0 0 0 0

low thres.:  
bad tracer

high thres.:  
good tracer





# Algorithms: Guess (NWP)

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NWP input is (by now) mandatory .

- **p-T fields** interpolated to centre of each tracer: level assignment.
- **p-(u,v) fields** interpolated to centre and level of each tracer: reduce tracking area.  
*(full tracking could be too time consuming, nevertheless: guess dependence kept marginal).*  
Also needed at the flagging step (partial guess QI).
- SAFNWC NWCLIB routines are used (\*).

# Algorithms: Tracers level

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- The basic input is: **mean IR10.8-channel temperature for "bright" pixels** (provided by the tracer-characteristics method), converted to pressure.

*(these pixels considered as a significant part of the cloudy pixels being tracked).*

- A "cloud base" is extrapolated for low levels  $>700\text{hPa}$  (\*).

*(low level winds known as close to wind at cloud-base level).*

- A "cloud top" is preferred for high levels  $<400\text{hPa}$  (the coldest pixels).
- **Note:** IR-channel at 3km vs. HRV at 1km, Ci cloudiness less transparent IR than VIS (\*\*).

# Algorithms: Tracking

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- The tracers (selected square segments, HRV region,  $t-\Delta t$  slot) are matched to tracking candidates (same size segments at  $t$ -slot, until a "reasonable" search distance) by 2 methods:

**Summed squared difference:** used for "big" tracers (basic processing, basic scale).

*(faster matching).*

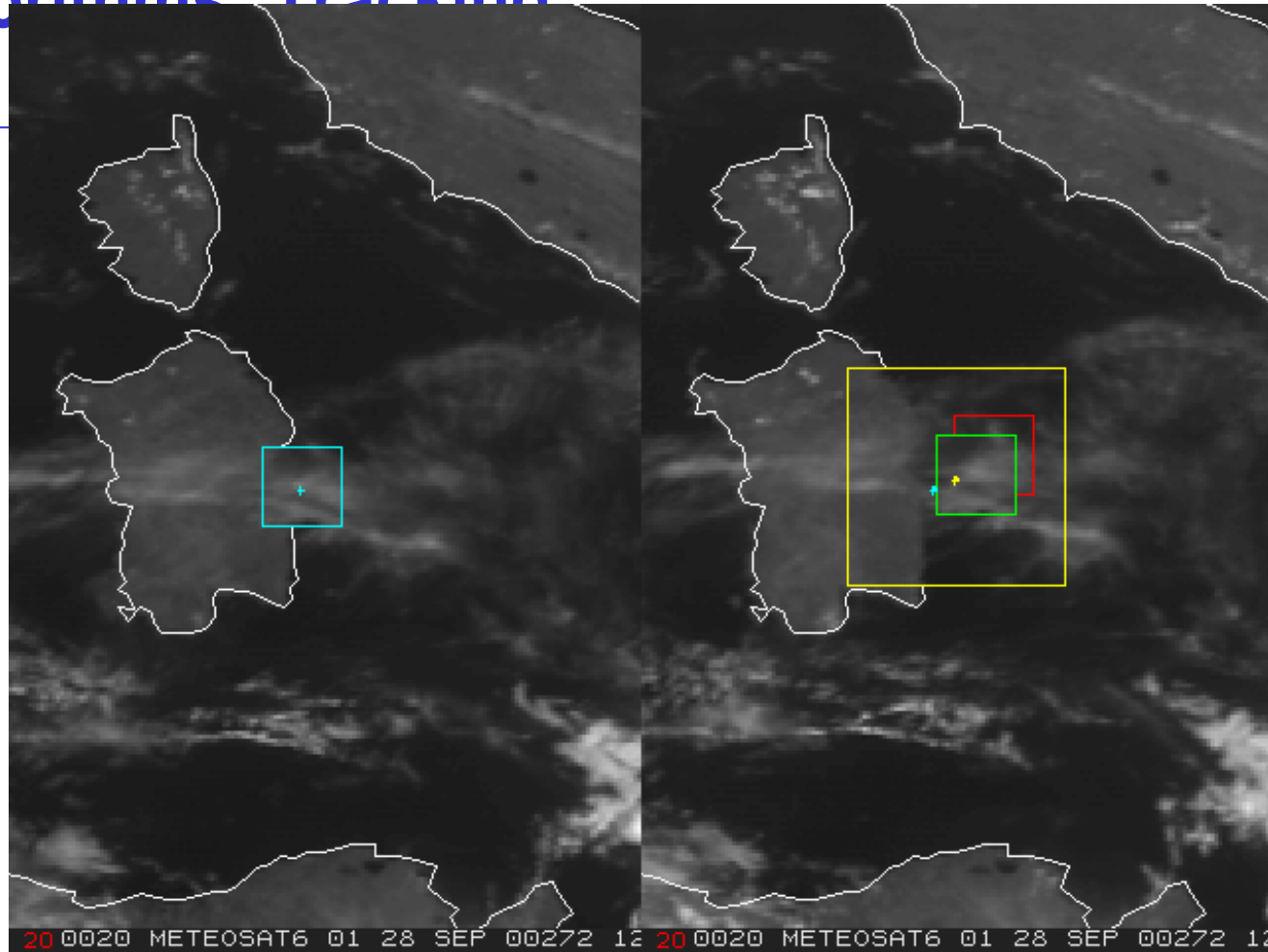
**Cross correlation:** for "small" tracers (additional processing for the fine scale).

*(more effective matching).*

- The best match and up to 2 other tracking centres, are kept: **up to 3 candidate-winds per tracer.**

*(to then perform a final selection step)*

# Algorithms: Tracking



First image

Second image

# Algorithms: Flagging

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- Use of **Quality Indicators method** (QI, Holmund 1998, used at EUMETSAT, adapted in several aspects to HRW) (\*).  
*(method well known and quite efficient).*
- Normalised **tests on consistency** are (if possible) computed:
  - In space (comparison to neighbours t-slot winds, an independent 2 scales spatial test is possible for some fine-scale winds) (\*\*).
  - In time (comparison to a close wind in the t-  $\Delta t$  slot set of HRW results).
  - To forecast (NWP).
- The final QI is the **weighted sum** of partial QIs. Given not all test is possible for any wind, an indicator "tests passed" is also added to the QI (\*\*\*)).

## Algorithms: ... And Selection

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- Up to 3 winds per tracer were tracked and flagged, **only one wind per tracer** is kept for output in the HRW bulletin (BUFR code).

*(implies less information but more straightforward to use).*

- The (default) way of selecting is: to keep **the best at most selection criteria** (up to 6):
  - Best matching.
  - Less change in tracer characteristics.
  - And the best at each partial QIs (up to 4).
- If not yet decisive: the one (significantly) more consistent when compared to the guess. Or the best tracking.

# Relevant implementation issues in PGE09

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- **A 2-scales procedure** (default):
  - 24px coarse scale and 12px fine scale (\*).
  - Most of the procedure is performed twice, similar (\*\*).
  - Search of fine-scale tracers: where no coarse scale tracer found, or it is "wide" (\*\*\*)).
  - "Inter-scale" spatial consistency test tried for fine-scale winds in the case of "wide".

*(fine-scale complementary to coarse: where no coarse, or it suggests more detail in wind field can be reached).*

- The HRW output composed of 2 datasets (BUFR bulletins):
  - **Basic winds:** coarse-scale winds (SAFNWC\_...\_B.buf).
  - **Detailed winds:** fine-scale winds, plus coarse non wide-tracer winds (^) (SAFNWC\_...\_D.buf).

*("secure" vs. "dense" wind datasets).*

- Tracers step is implemented as the final step (t-slot preprocessing for  $t + \Delta t$  HRW winds).

# Examples for different conditions or cloudiness

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Lee cloud conditions.

Convection at different stages of development.

Cloudiness related to small-scale circulation.

Low sun elevation.

Slant satellite viewing angle.

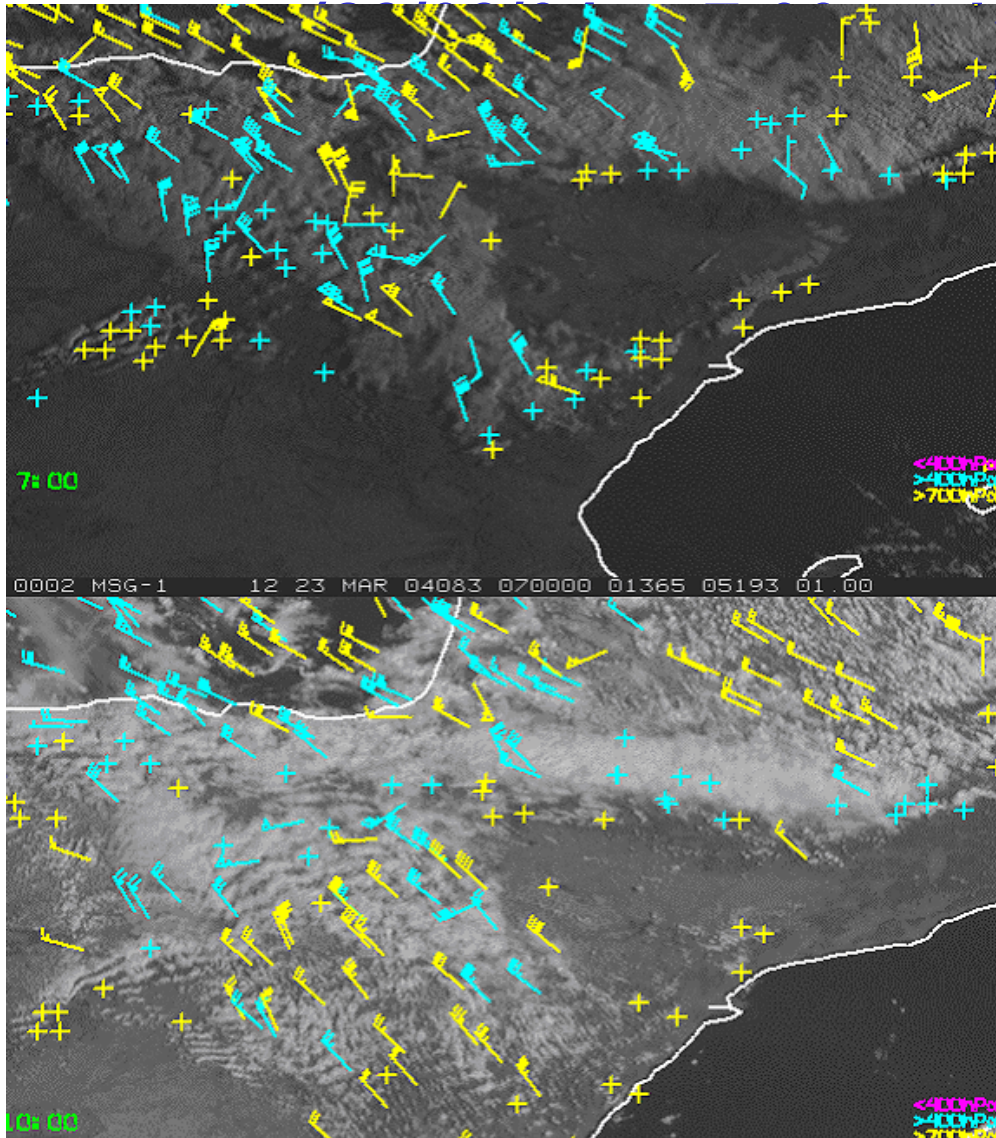
Frontal systems (including semi-transparent Ci).

**Display:**

QI > 59% :    >700hPa.    700-400hPa.    <400hPa.  
(QI 50-59%)

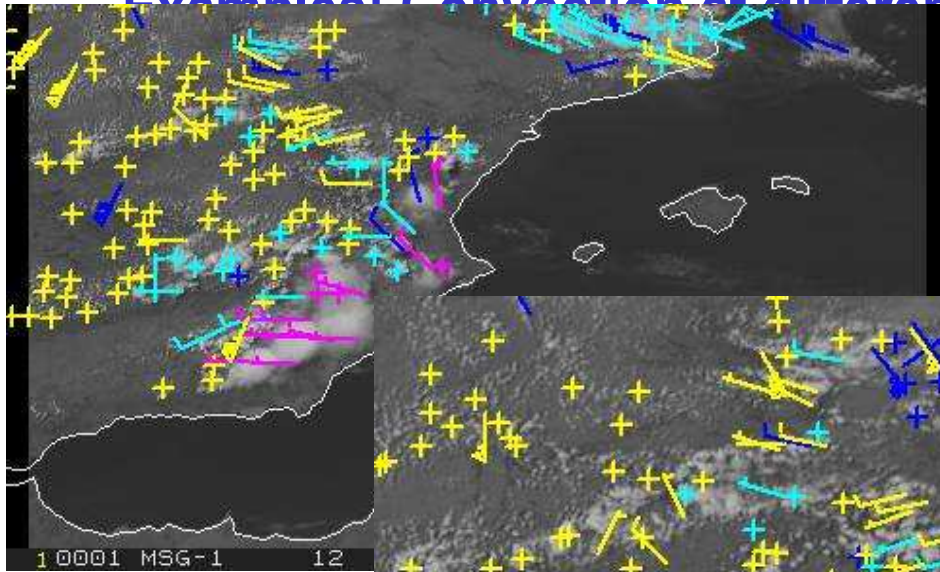


# Examples: Lee cloud conditions (10:00 UTC)

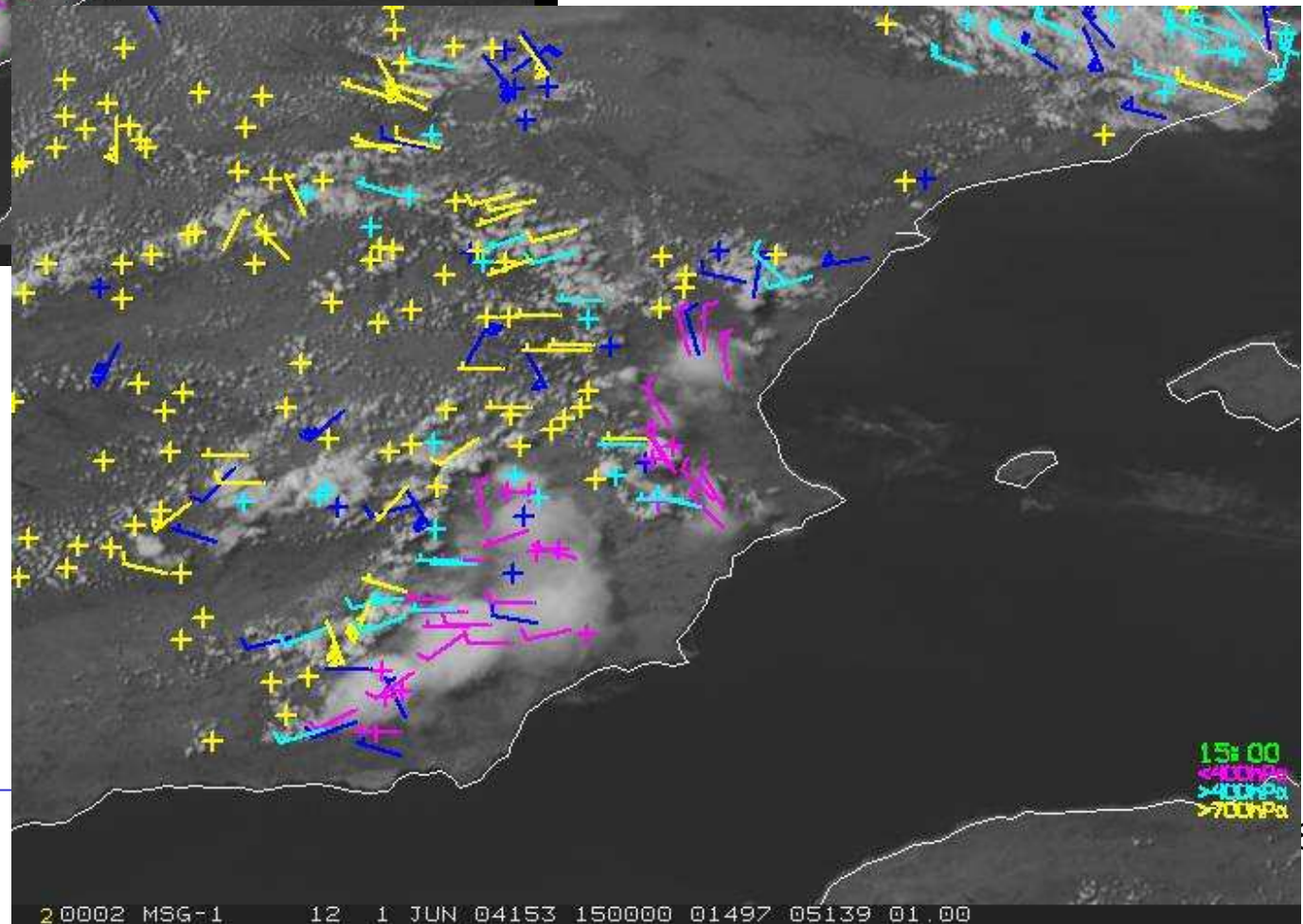


Detailed winds

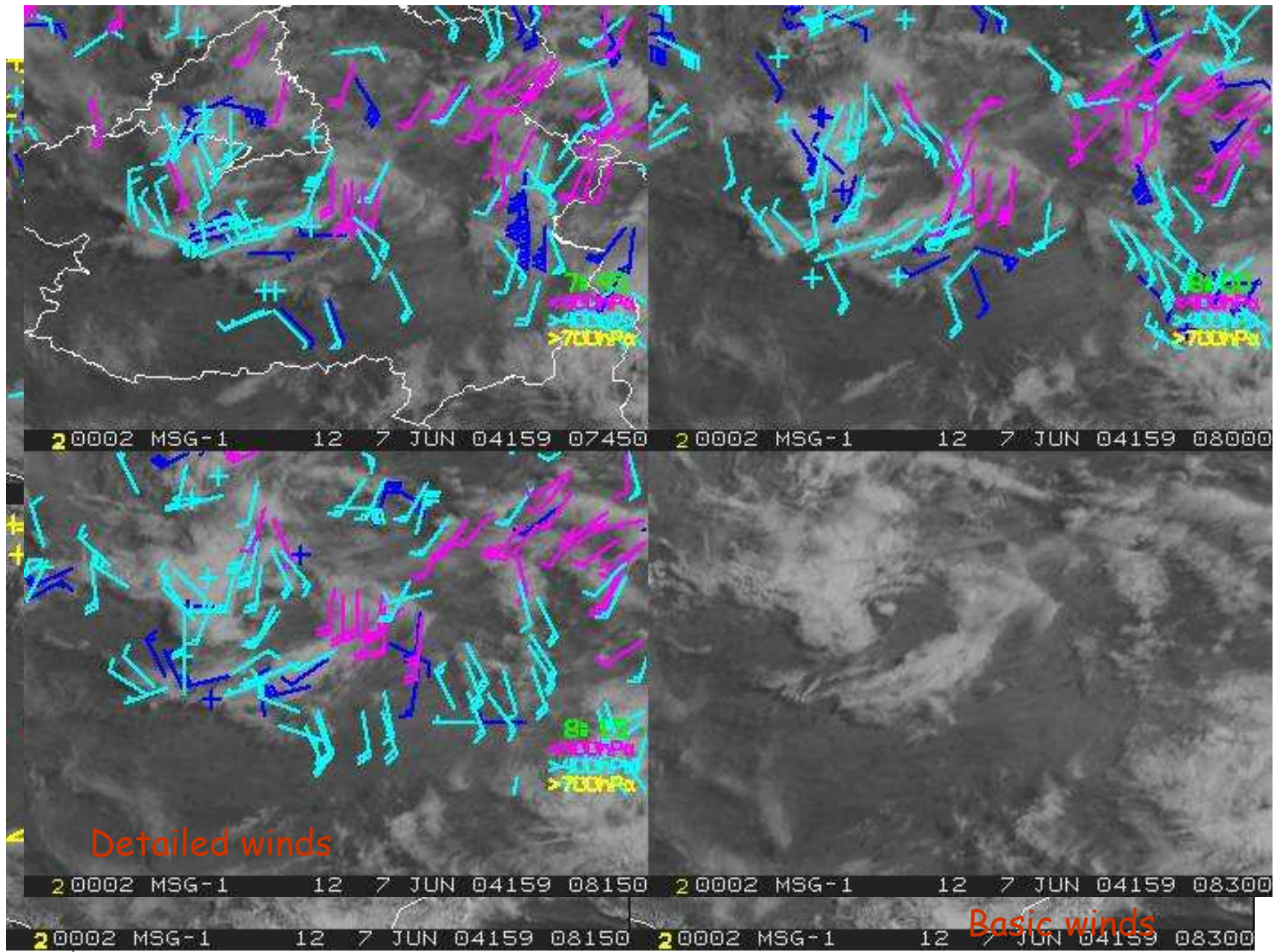
# Examples: Convective at different stages of development (5:00)



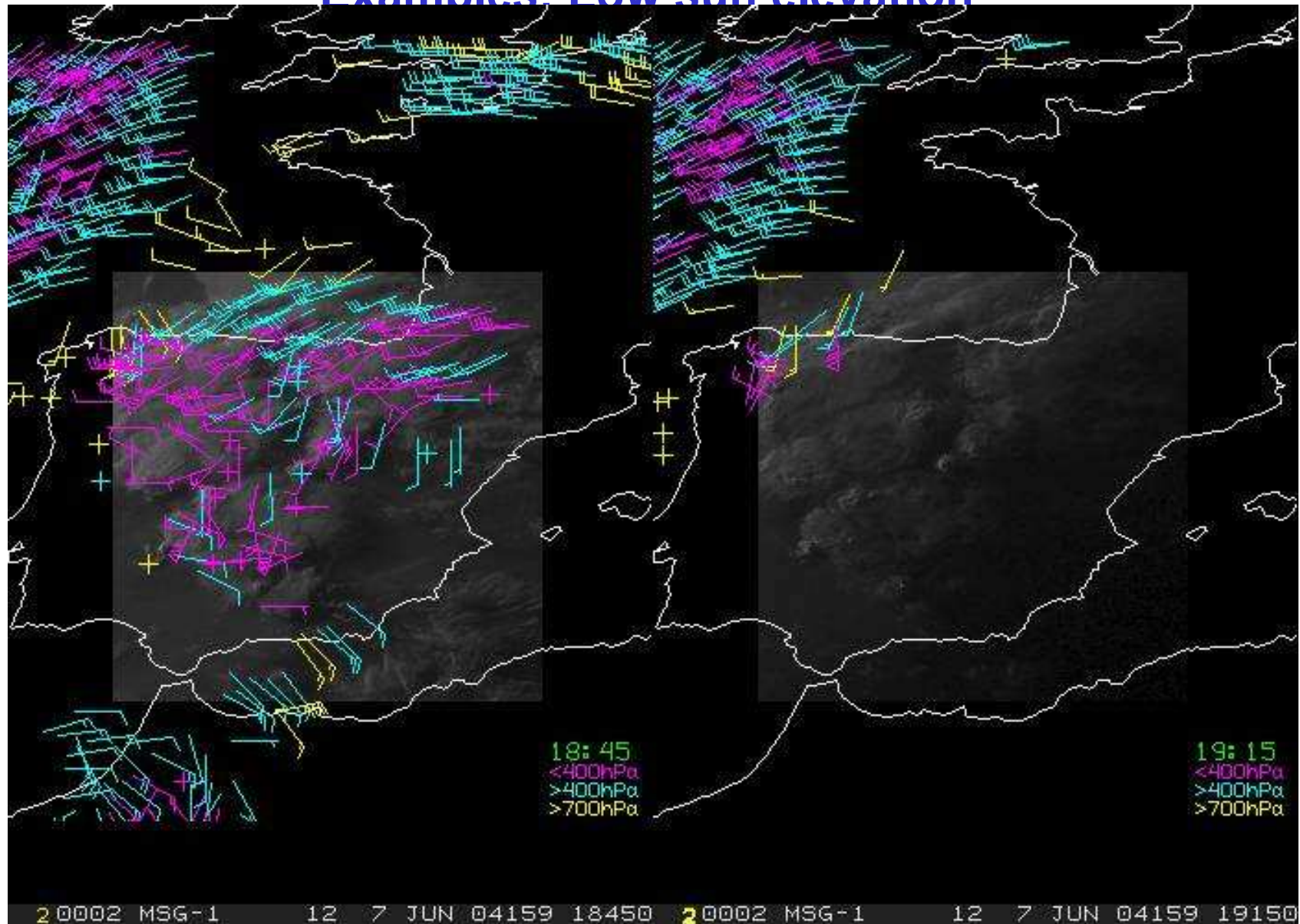
Basic winds



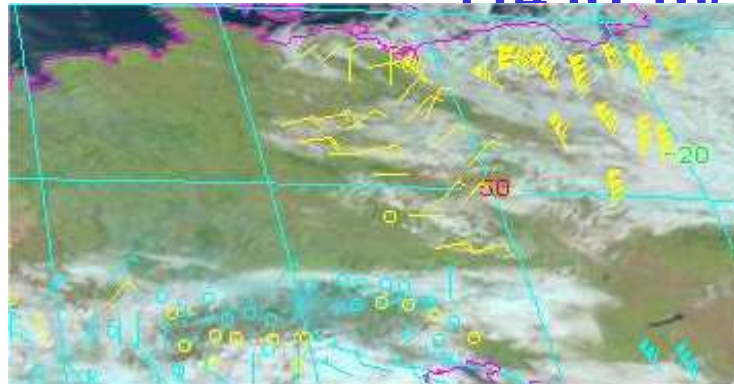
Detailed winds



## Examples: Low sun elevation

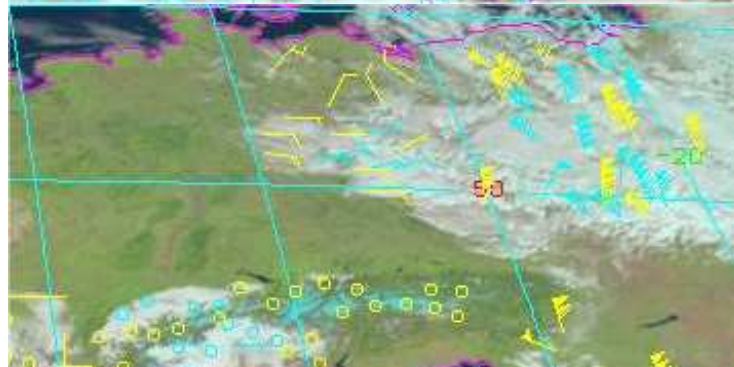


# Examples: Slant satellite viewing angle (14 to 16/10/03 at 10:00 UTC)

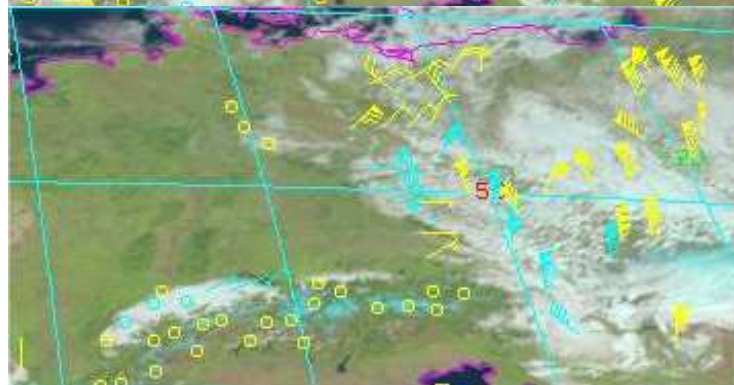


Basic

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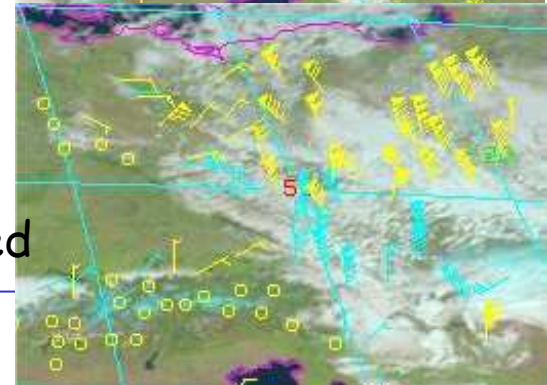
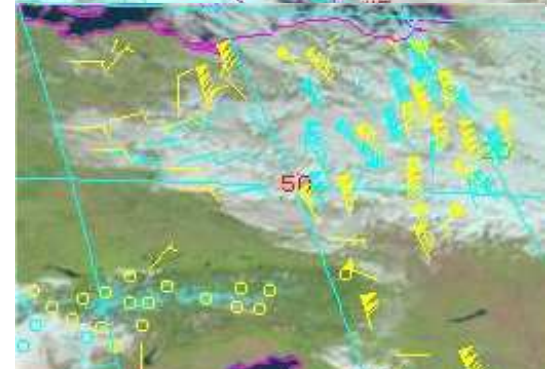
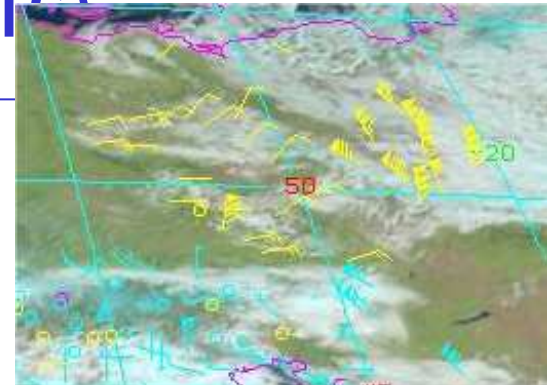


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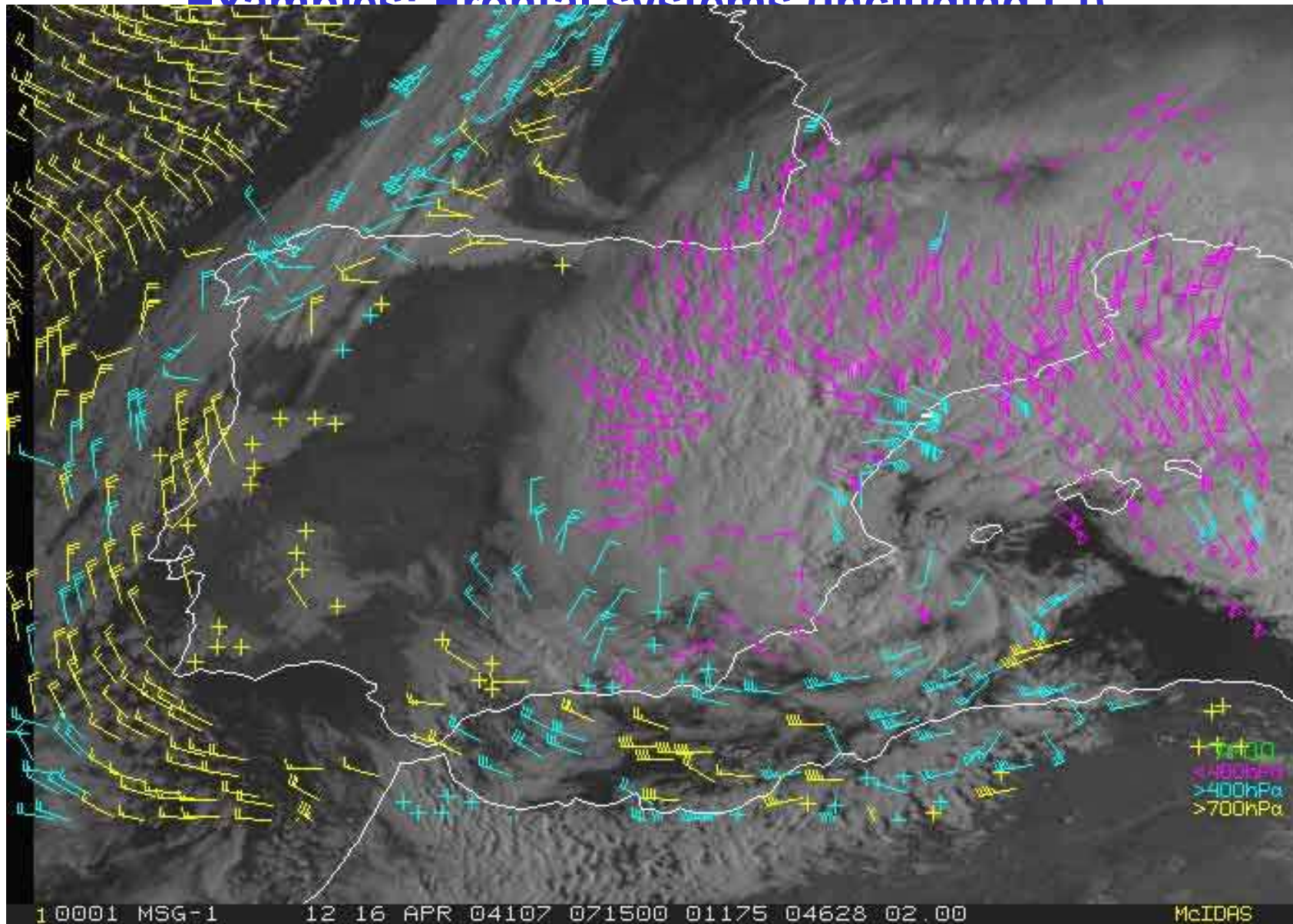


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Detailed



## Examples: Frontal systems (including Ci)



# Some known problems

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- “**Ground tracers**” (most evident in case of snow). Others: **ground-influenced** cloudiness.
- The “high” normalised threshold requested (same land and sea) misses some low-level cloudiness **not bright enough** to give tracers (e.g. many Sc, could also present large extensions of little contrast).
- The HRW detailed wind pattern still **not as “high resolution”** as could be desired (e.g. fields of small Cu likely giving few tracers with the described methods). Also, more often than in the case of basic winds, erroneous detailed winds reach a QI of 60%.
- A **fixed QI reference threshold** (60%) (despite the disparity in processing conditions, and applied QI tests, etc.) (\*).
- The level-assignment **based on IR information**.
- (HRV mis-registration image to image: not yet clear cause of error since MSG data operational).

## Options not in the default configuration

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- **Wind continuity:**
  - Tracers step: at each location, first looks close (in position, level, at same scale and same tracer method) to final location of any wind  $t-\Delta t$ : "**persistent tracer**". Otherwise tries for a **new tracer**.
  - Time consistency QI tests: only for persistent tracers.  
*(time consistency closer to EUMETSAT's symmetry test; provides some tracers' trajectories and durations).*
  - **But:** time consuming (more new tracers than expected): a sub-region for the fine-scale is advised in this option.
- **Single-scale procedure** (similar to coarse-only, at 20 pixel resolution or better):  
*(a compromise, and faster, but gives "less complete" results).*
  - Wind selection on best QI (space&time) (PGE09 v0.0) (\*).

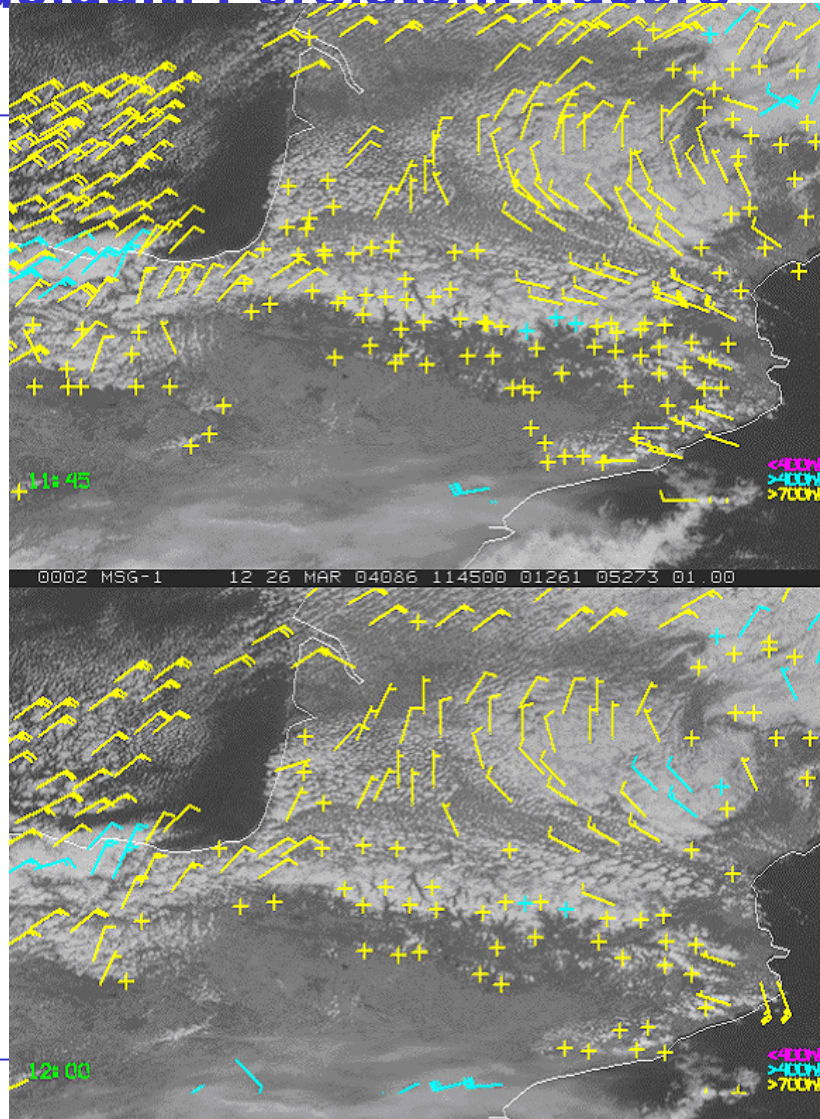


## Options not in the default: Persistent tracers

Using Continuity option

Basic winds dataset,  
26/03/04

Using Default



## Further development work (\*)

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- Addition of **a terrain-influence flag** (Fernández, 2003)(\*\*), identifying:
  - Possibly non-cloud tracer (just land feature) (but also: plans to use cloud-top product CTTH)
  - Tracer possibly blocked by terrain (could perhaps give non realistic winds)
  - Tracer likely in presence of gravity wave conditions (could give non realistic wind)
- **New work** (2004):
  - Improvement of lee-wave conditions flagging (avoid fixed vertical lapse- rate and -maybe- fixed distance to obstacle).
  - Use of terrain-influence flag in wind selection.
  - Use of CTTH, as option for level-assignment.

Furt

