

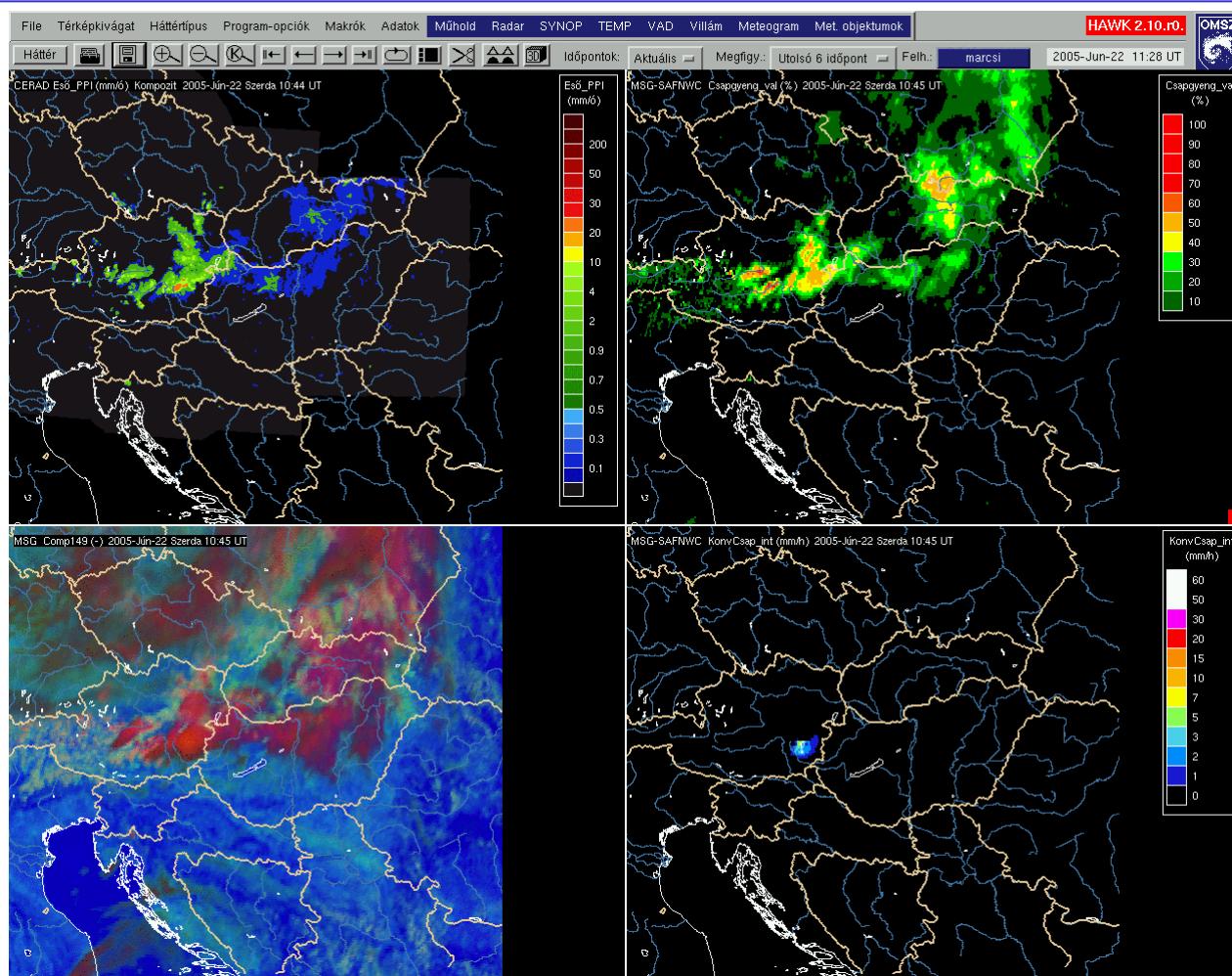
PGE04-MSG Precipitating Clouds Product

**Presented during the NWCSAF Product
Assessment Review Workshop**

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Example of Precipitating Cloud Product



PC output:
Likelihood
of precipitation
10%
20%
30%
40%
50%
60-100%

22 June 2005 10:45UTC

SAFNWC/MSG v1.2
Radar composite (upper left)
PC day algorithm (upper right)
RGB14r9 (lower left)
CRR (lower right)

(Courtesy of HMS, M. Putsay)

Product and verification history

- V1.0/1.1: algorithm derived from AVHRR algorithm coefficients tuned on BALTRAD radar, 2 intensity classes, but obvious that 2 classes could not be resolved
- V1.2: tuned with MSG data on European SYNOP current weather report (WW), only total precipitation likelihood.
verified against 1 year French and one year Hungarian rain gauge data
- V1.2F: different tuning of 1.2 algorithm coefficients on french gauge data, verified against one year of Hungarian gauge data.

Performance v1.2 – subjective -

- Extend of precipitation generally overestimated
- Day and night algorithm still discontinuous
- Day algorithm outperforms night algorithm
- Problems at low sun: underestimation of precipitation
- Performance depends on synoptic situation:
 - isolated convection OK
 - weak fronts often usefull
 - strong fronts useless (fronts visible but precipitation quite uniform over all frontal cloud system)

Verification method

Classification into rain/norain performed at fixed likelihood thresholds:

	Satellite rain	Satellite no rain
Gauge rain	Hits	misses
Gauge no rain	False alarms	Correct negatives

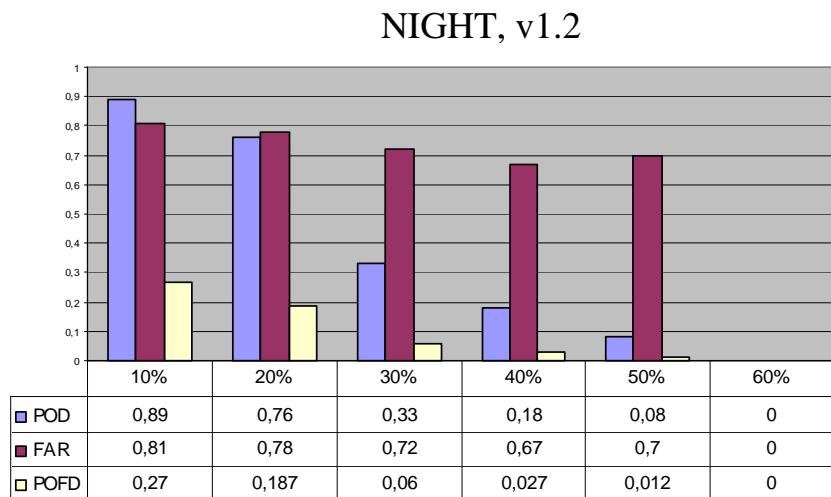
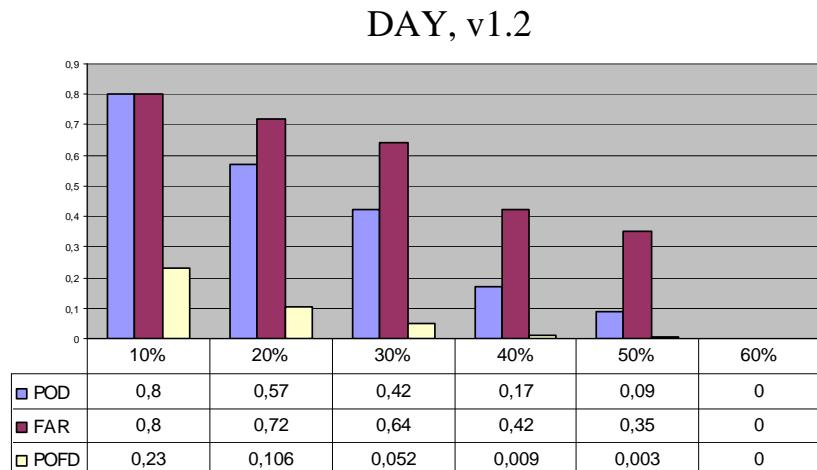
Scores presented:

Probability of detection:
 $POD = \text{hits} / (\text{hits} + \text{misses})$

False alarm rate:
 $FAR = \text{false alarms} / (\text{false alarms} + \text{hits})$

Probability of false detection:
 $POFD = \text{false alarms} / (\text{correct negatives} + \text{false alarms})$

Algorithm performance v1.2 at different likelihood thresholds, reference: hungarian gauges 2004



Conclusions

Day algorithm: both POD and FAR decrease with more severe likelihood threshold for precipitation identification, but POD decreases more than FAR

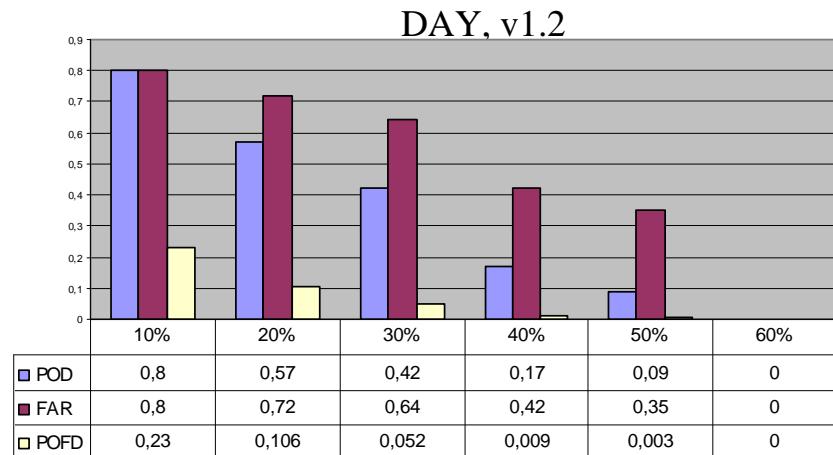
Night algorithm: both POD decreases similar as in day algorithm, but FAR remains almost Constantly high.



Recommended threshold both day and night:
20%

At this threshold the night algorithm outperforms the day algorithm!

Algorithm performance v1.2 day versus 1.2F day at different likelihood thresholds, reference: hungarian gauges 2004

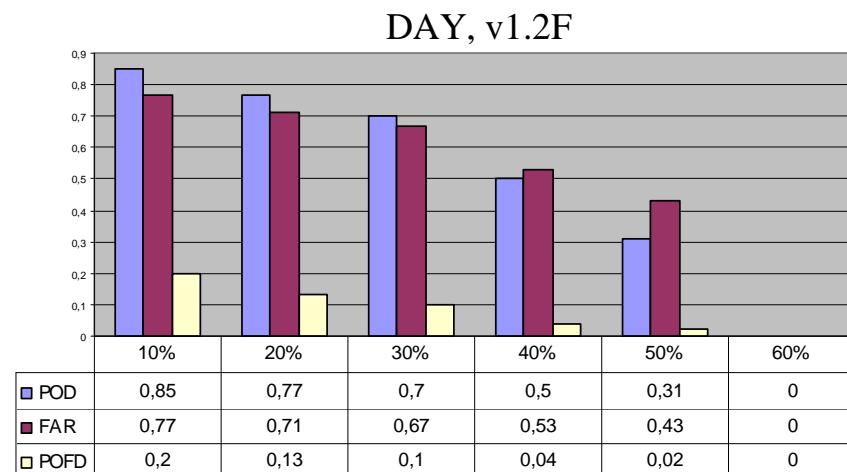


1.2F: tuned on French rain gauge data

Conclusions

As compared to v1.2 day, advantages of v1.2F are:

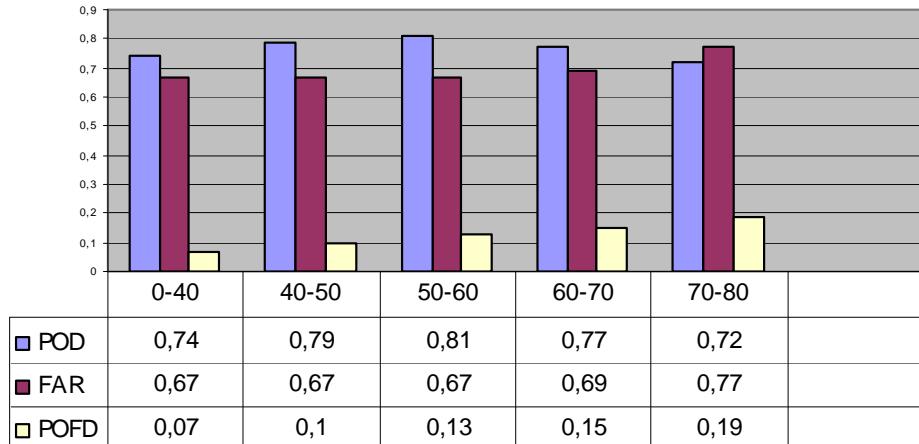
- Significantly higher POD at all thresholds ★
- Up to 30% threshold is POD higher than FAR★



Recommended threshold for v1.2F day:
**day algorithm better at 30%,
At 20% similar to night algorithm**

Algorithm performance at different sun zenith angles, reference: hungarian gauges 2004, likelihood threshold 20%

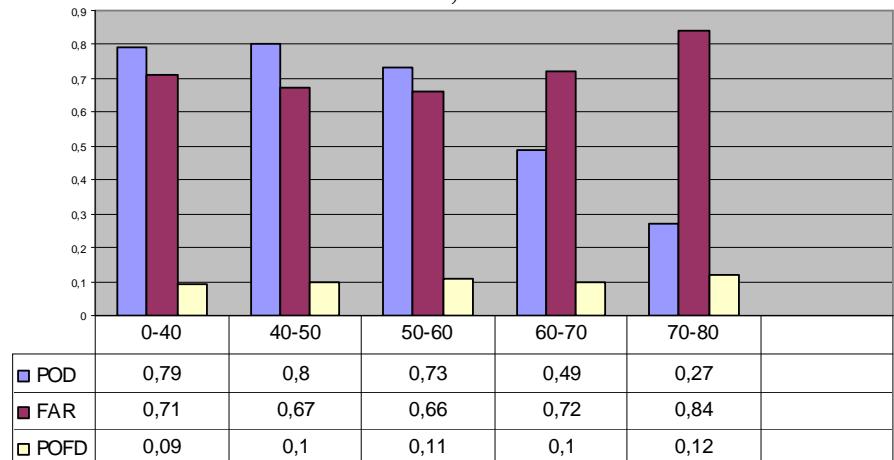
DAY, v1.2F, gauge tuned



Conclusions

Day algorithm 1.2F gauge tuned:
No pronounced angular dependence ★

DAY, v1.2

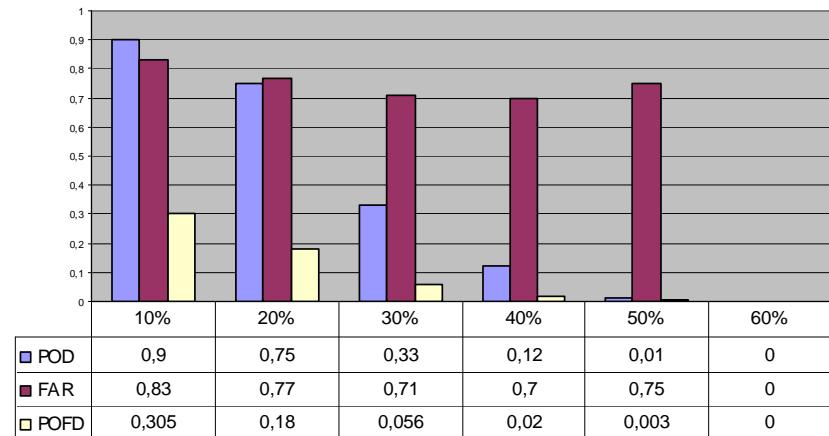


Day algorithm 1.2: pronounced angular dependence ☹

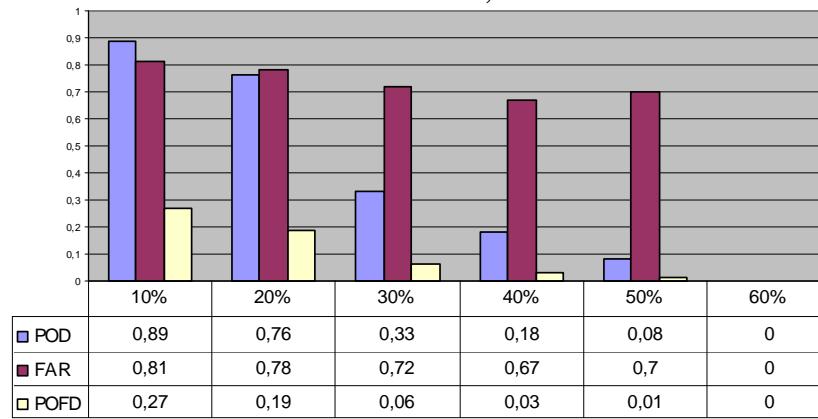
Gauge tuned day algorithm clearly outperforms v1.2!

Algorithm performance v1.2 night versus 1.2F night at different likelihood thresholds, reference: hungarian gauges 2004

NIGHT, v1.2



NIGHT, v1.2F



1.2F: tuned on French rain gauge data

Night algorithms v1.2 and v1.2F:

Comparable performance

Summary

- New gauge tuned coefficients give much better performance during day than current 1.2 algorithm.
Installation: replace current auxilary data directory for PGE04 with update (soon available on helpdesk)
- Problem with day-night discontinuity not solved, night algorithm inferior
- Product useless for strong fronts (no hope for improvement when considering spectral features only)

Outlook for 2.0

- Investigate how much the night algorithm can be improved by using 3.9 μ m channel
- In case of significant improvements for night, the scheme would have to be split in day/ twilight/ night
- It is however not likely that discontinuities between day/ twilight/ night would be less than in v1.2 between day and night.