

NWCSAF/GEO: Suspended dust detection

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Cliquez pour ajouter un texte
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2020**

Outline

- Introduction : Dust flag in CMA product
- Algorithm Description
- Validation
- Preparation for MTG

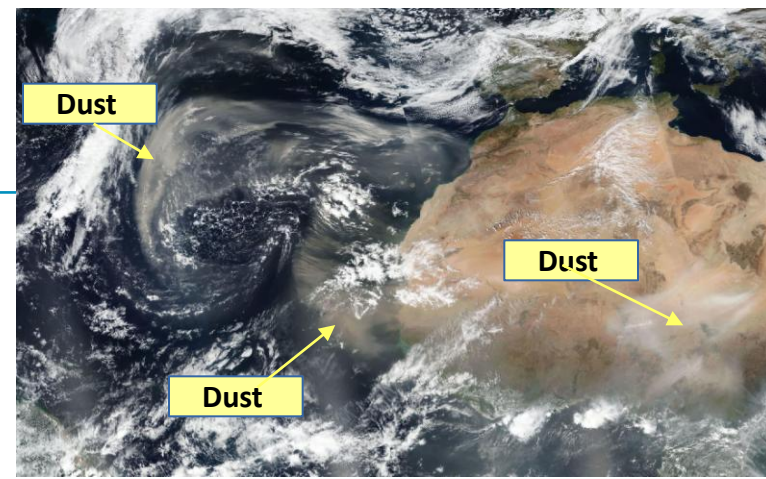
Introduction

Dust detection in NWCSAF-GEO :

- Variable : cma_dust accessible in CMA product
- flag data : 0 → no dust
 - 1 → dust
 - 2 → undefined
 - 255 → no determined
- Available for all pixels for each satellite slot
- Performed according to three different algorithms depending on the conditions : day on sea, day over land and night on sea
- Currently, there is no detection at night over land and in twilight area
- NWCSAF-GEO V2018 allows the processing of several geostationary satellite : MSG, Himawari and Goes

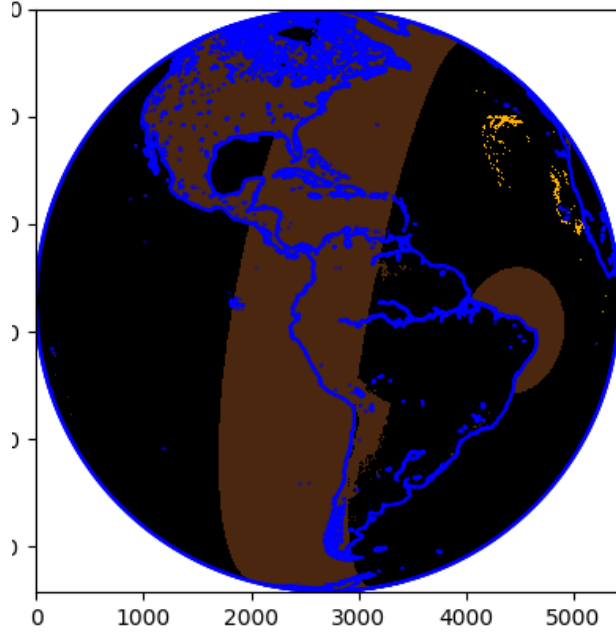
Introduction

- No computed
- No dust
- Dust



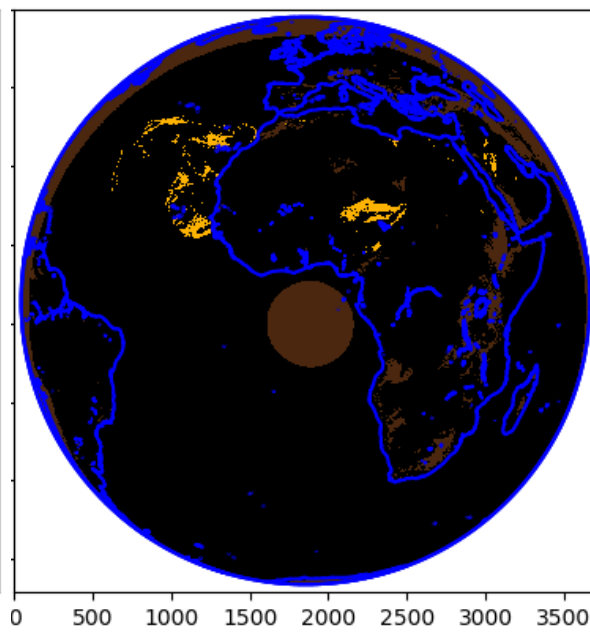
True Color NPP/Viirs : 20200225

GOES16 20200225 12H



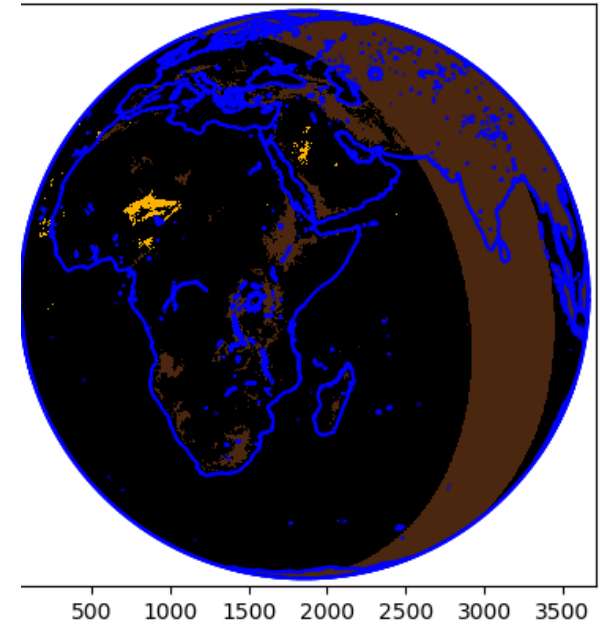
GOES16

MSG4 20200225 12H



MSG4

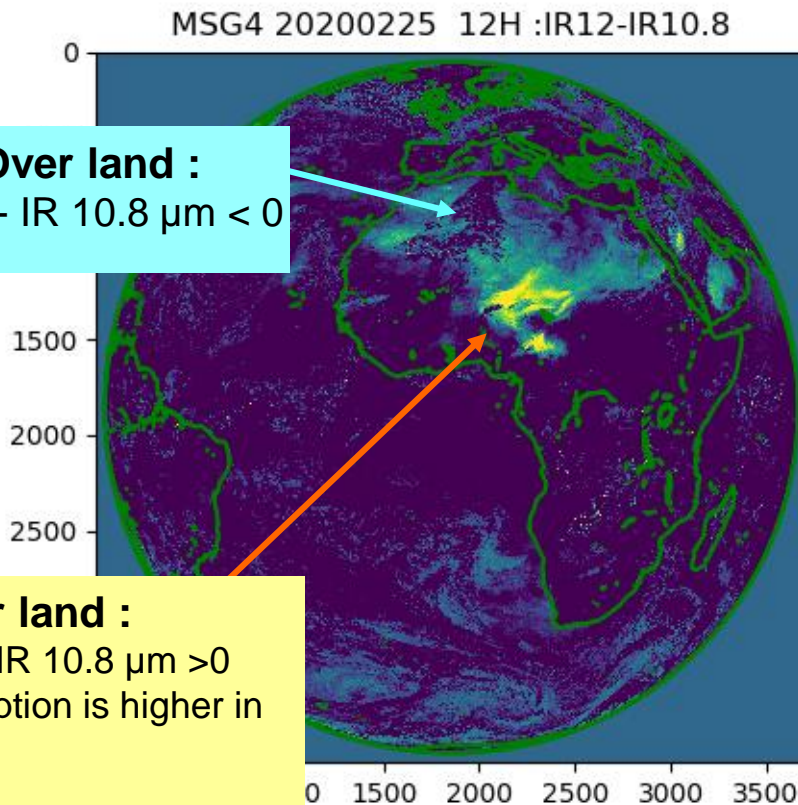
MSG1 20200225 12H



MSG1 (IODC)

Algorithm description : thresholding method

By day over land



Dust detection

- thresholds on BT differences :
 $\text{IR } 3.9 \mu\text{m} - \text{IR } 10.8 \mu\text{m}$
 $\text{IR } 12 \mu\text{m} - \text{IR } 10.8 \mu\text{m}$
- threshold on the ration :
 $\text{vis} 0.6 \mu\text{m} / \text{Nir } 1.6 \mu\text{m}$
- Spatial homogeneity of visible
reflectance : threshold on infrared
and visible variance

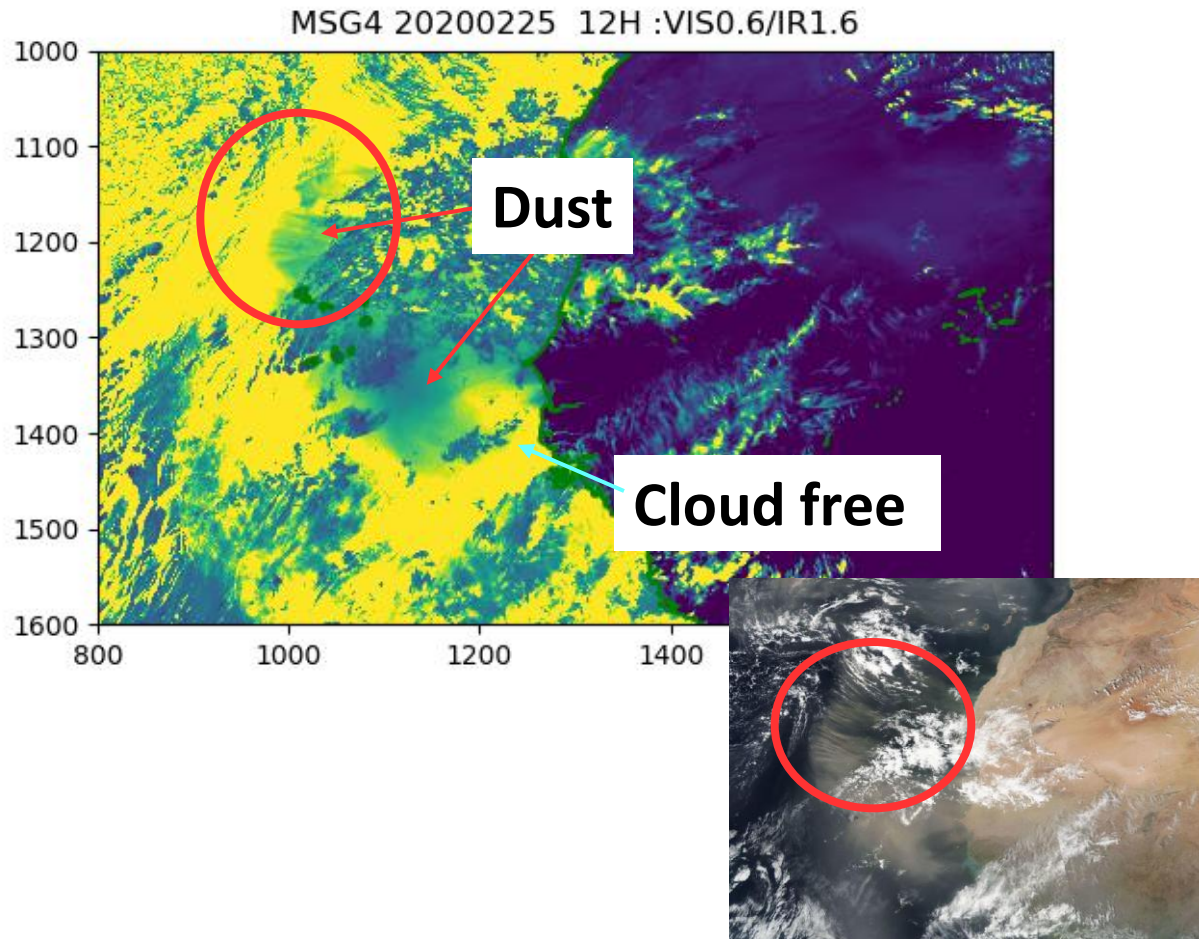
To limit false alarms

- threshold on $\text{IR } 10.8 \mu\text{m}$, visible
 $0.6 \mu\text{m}$ (not too cold, not too bright)
- smooth in infrared and visible
channel

MSG04 : $\text{IR } 12 \mu\text{m} - \text{IR } 10.8 \mu\text{m}$ 2020 02 25 12h00

Algorithm Description : thresholding method

By day over sea



Dust detection

- threshold on differences between IR12 μ m - IR10.8 μ m
- threshold on the ratio vis 0.6 μ m / Nir 1.6 μ m
- threshold on infrared and visible variance

To limit false alarms :

- threshold on IR10.8 μ m (not too cold) ,
IR8.7 μ m -IR10.8 μ m (low cloud filter)
- threshold on reflectance (not too bright)

MSG04 : VIS 0.6 μ m/IR1.6 μ m

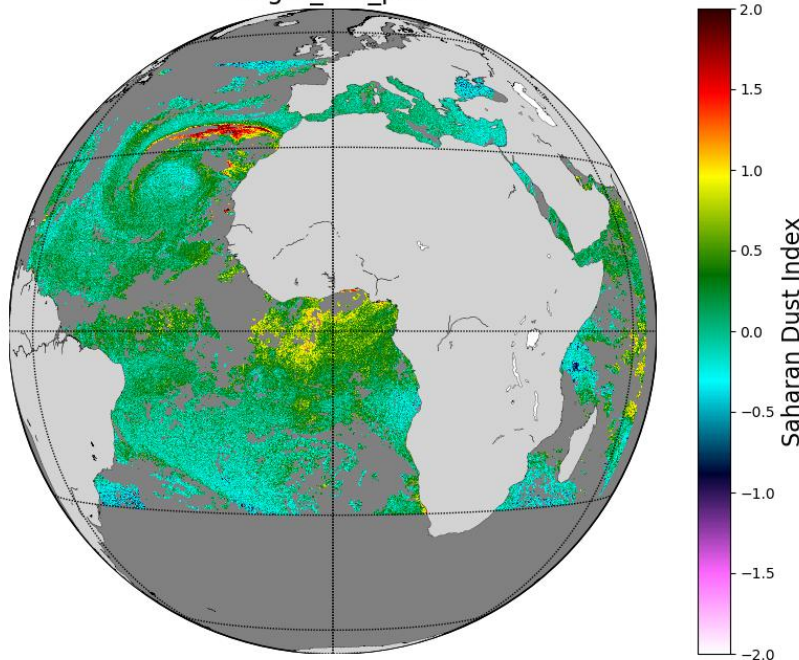
2020 02 25 12h00

Algorithm Description : thresholding method

By night over sea

Sahara Dust Index = $a * (ir_{10.8} - ir_{12}) + b * (ir_{3.9} - ir_{8.7}) + c$
(given by OSISAF)

Meteosat11, 20200225, Night,
Night_SDI_prd



mean = 0.128 std = 0.295 nbpts = 1852384

Dust detection

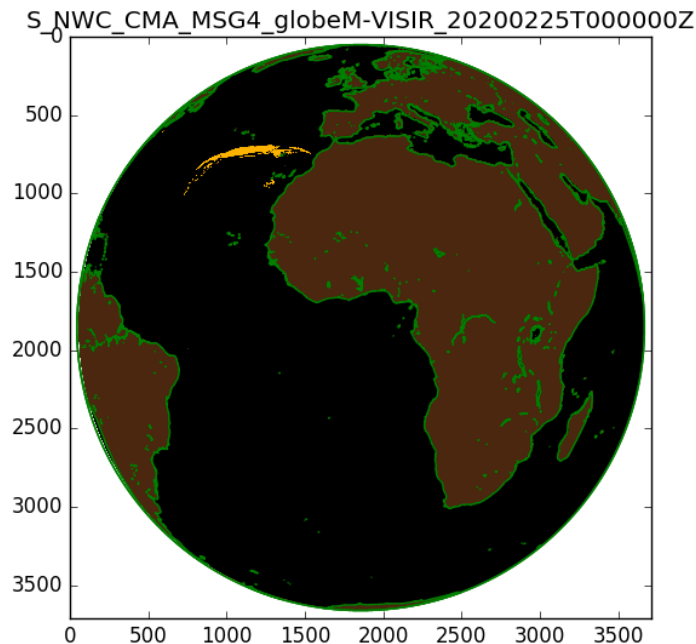
- threshold on SDI
- threshold on IR 10.8 μm – IR 3.9 μm

To limit false alarms

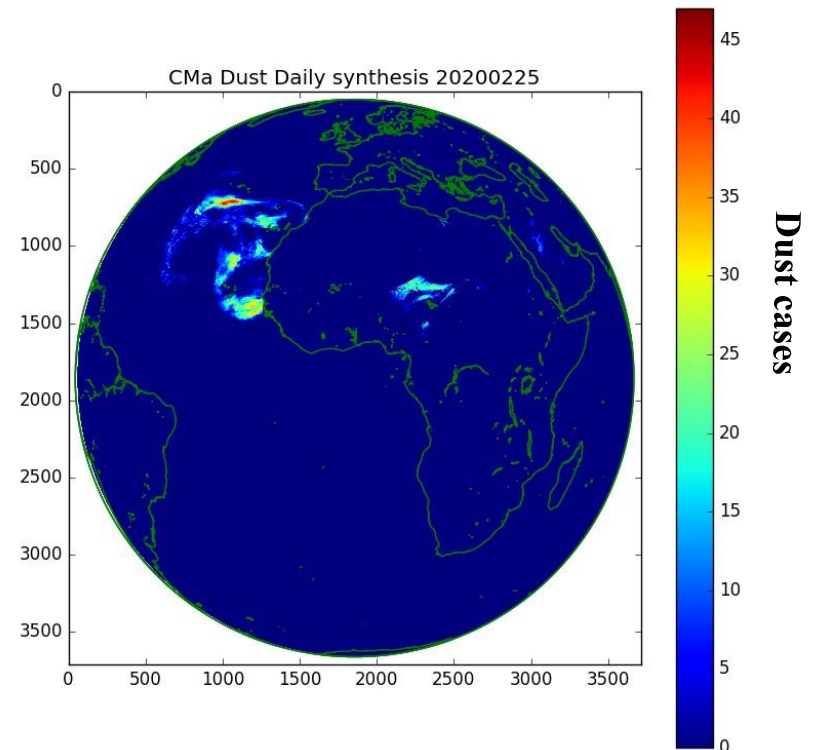
- thermal test (not too cold) :
threshold on IR 10.8 μm
- high cloud :
threshold on IR 10.8 μm – IR12 μm
- low cloud :
threshold on IR 8.7 μm - IR10.8 μm

Algorithm Description : thresholding method

CMA Dust flag : OPERATIONAL

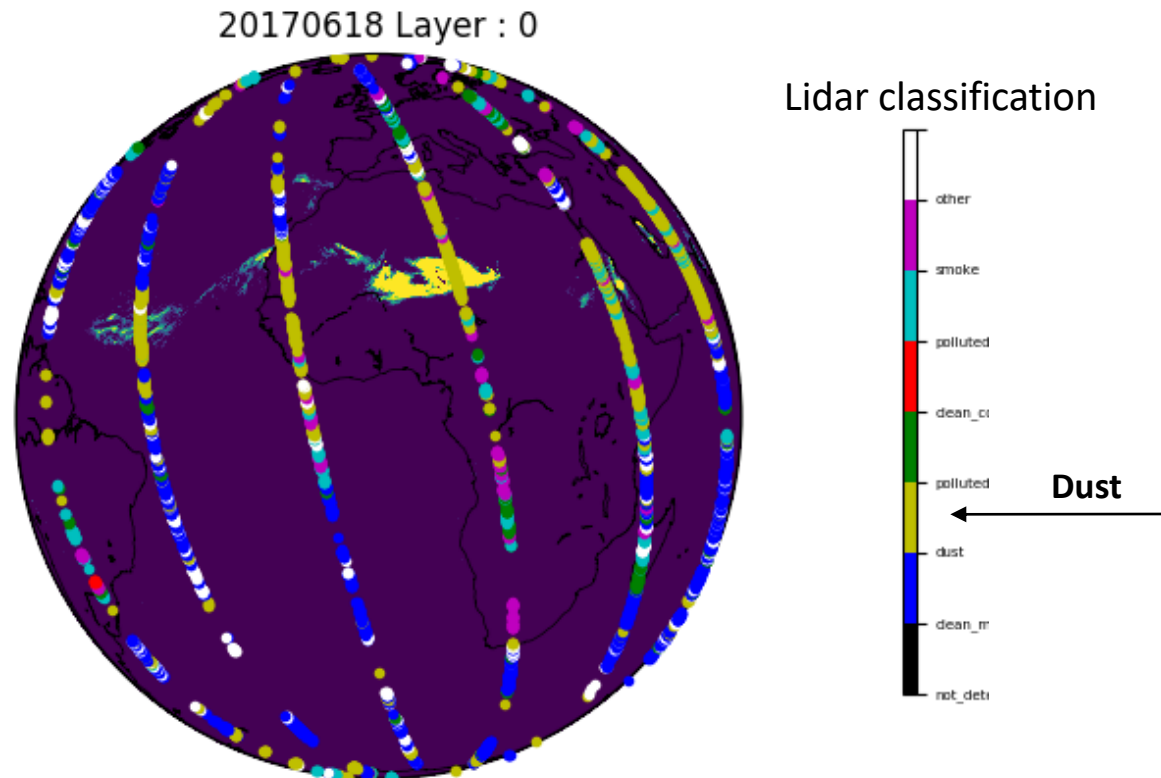


CMa Dust Daily synthesis



Validation : Method

CMa Dust daily synthesis + Lidar aerosols classification



Validation : Results

MSG3 CMA DUST	% of CMA Dust detections vs lidar detection	False Alarms
By day over sea	47 %	0 %
By day over land	5 %	0 %
By night over sea	31 %	0,01%

By day over land, CMA Dust flag only detects 5 % of lidar dust observations

No false alarms

Preparation for MTG : Algorithm improvements

Dust algorithm improvements for MTG :

By day over land :

- the thresholds have been reajusted
- a test on $8,7 \mu\text{m} - 10,8 \mu\text{m}$ and $3,9 \mu\text{m} - 8,7 \mu\text{m}$ have been added
- a threshold depending on solar angle has been added on the difference using $3,9 \mu\text{m}$: $3,9 \mu\text{m} - 10,8 \mu\text{m}$ (to limit degraded detections at low sun elevation (morning and evening))

By day over sea :

- thresholds have been reajusted

By night over sea :

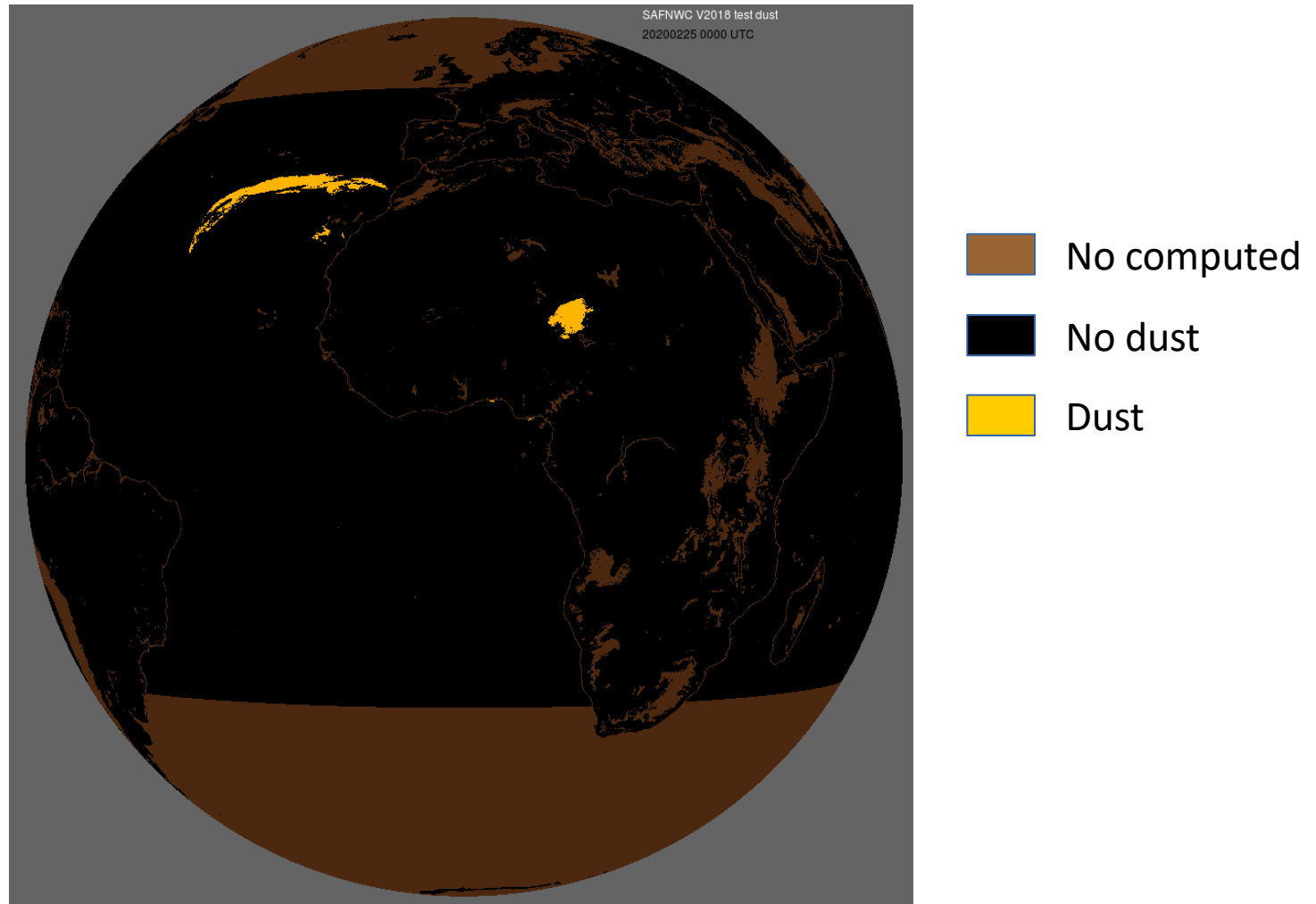
- threshold on SDI has been relaxed

By night over land :

- New algorithm has been created using simulations of brightness temperature with radiative transfert model (RTTOV) over clear sky

Preparation for MTG : Algorithm improvements

Dust flag with new algorithm :



Algorithm improvement by day and night +new algorithm by night over land :

MSG4 2020-02-25

Preparation for MTG : Algorithm improvements

MSG3 CMA DUST	% of CMA Dust detections vs lidar detection	False Detections
By day over sea	48 %	0 %
By day over land	12.5 %	0,04 %
By night over sea	37 %	0,01%
By night over land	6 %	0,01%

**Algorithm improvement by day and night +new algorithm by night over land :
Validation with MSG3 + lidar**

Channel from Goes16 and Himawari8 similar to those MTG :

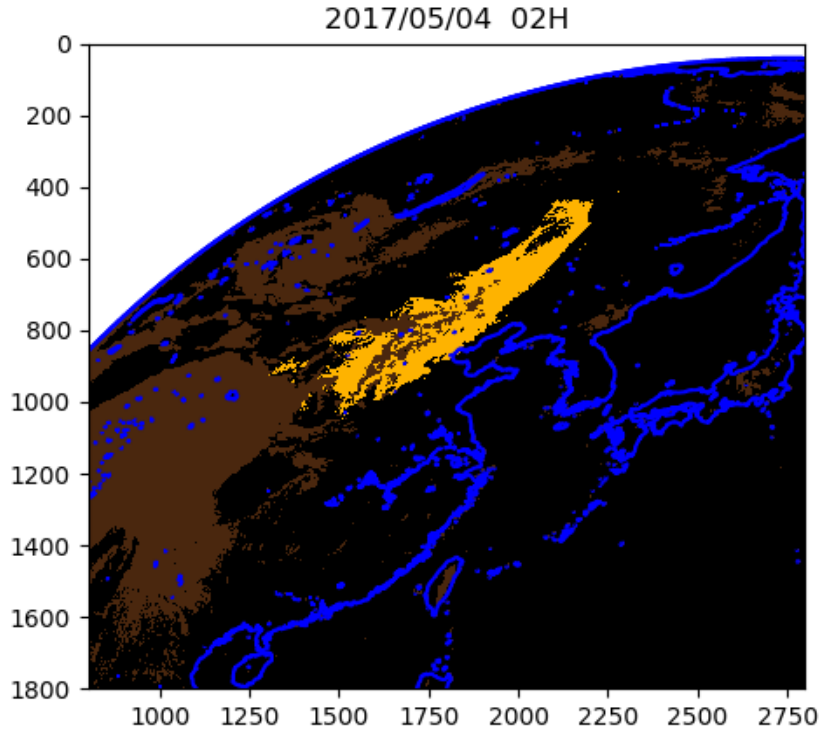
Test the new algorithm :

over land with Himawari 8

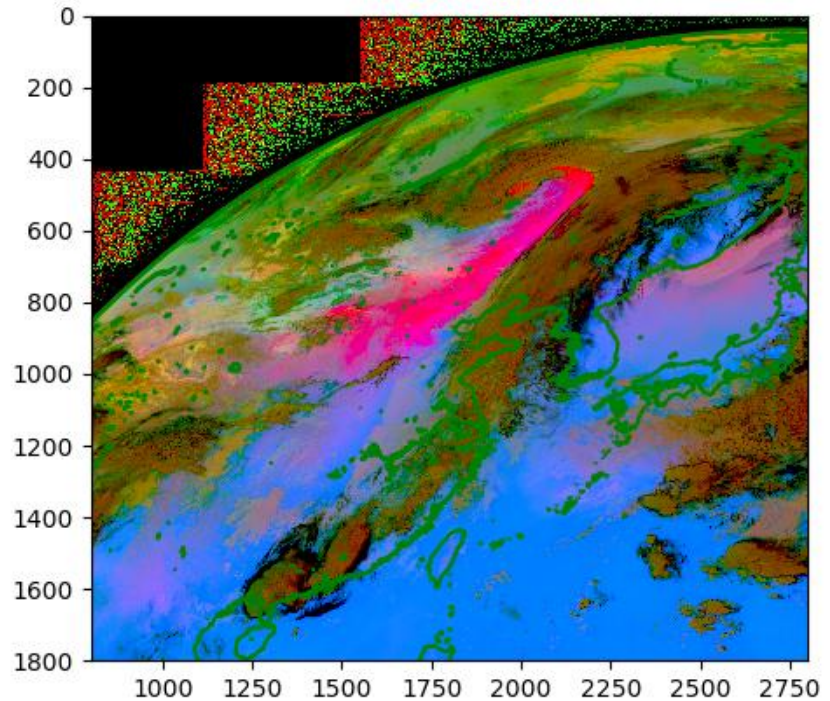
over sea with Goes 16

Preparation for MTG : new algorithm applied on Himawari 8

By Day



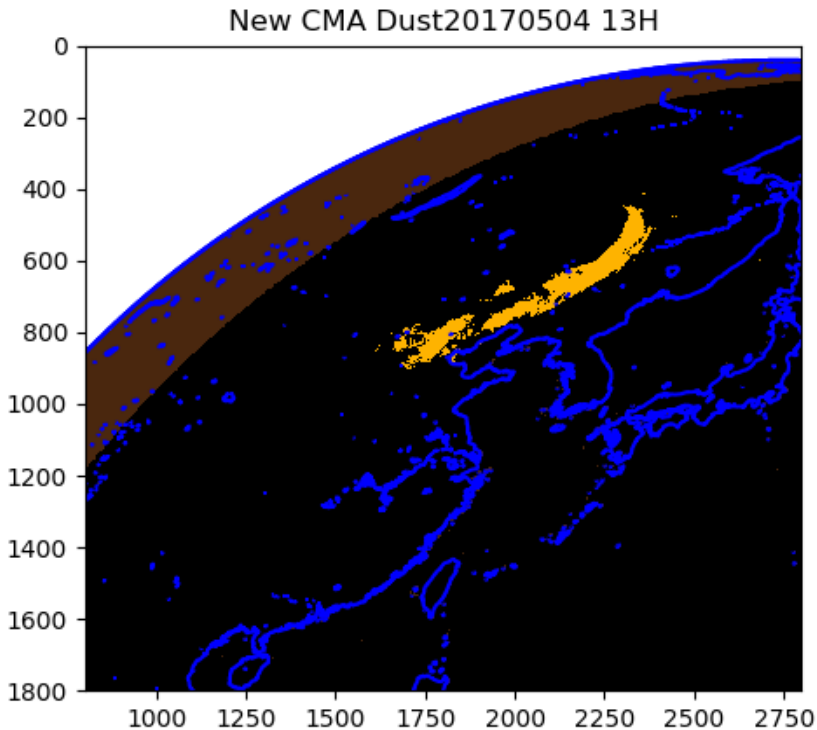
New algorithm applied with Himawari data



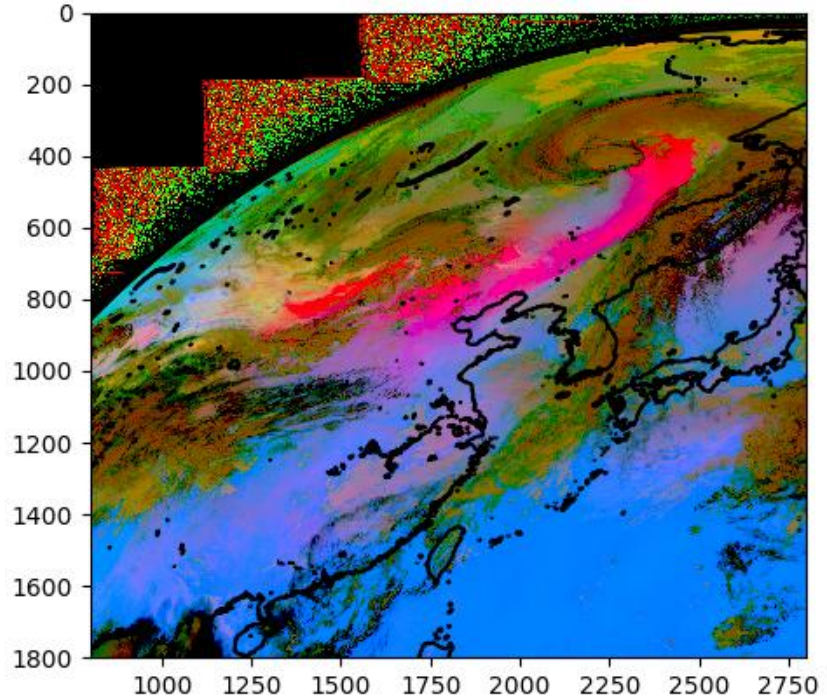
RGB dust

Preparation for MTG : new algorithm applied on Himawari 8

By Night

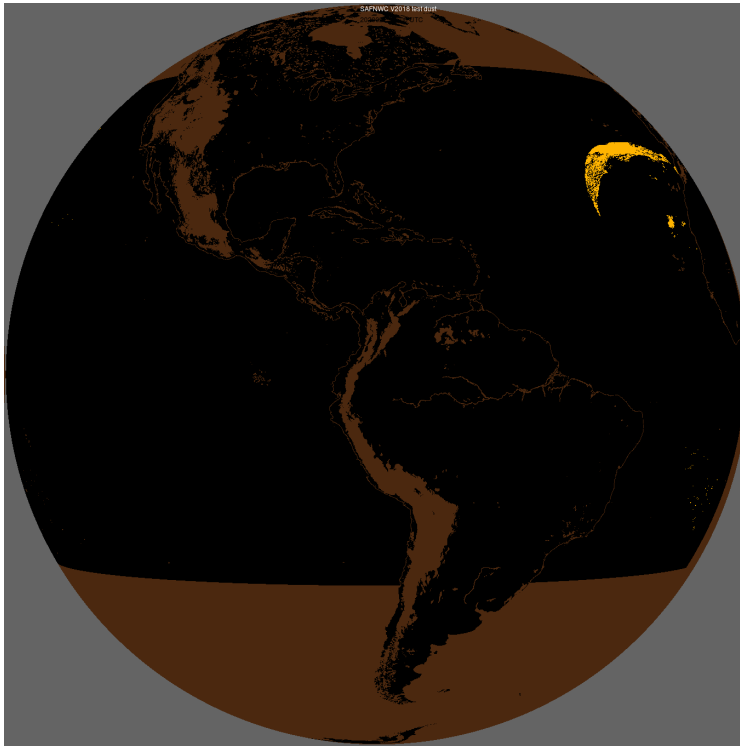


New algorithm applied with Himawari 8 data

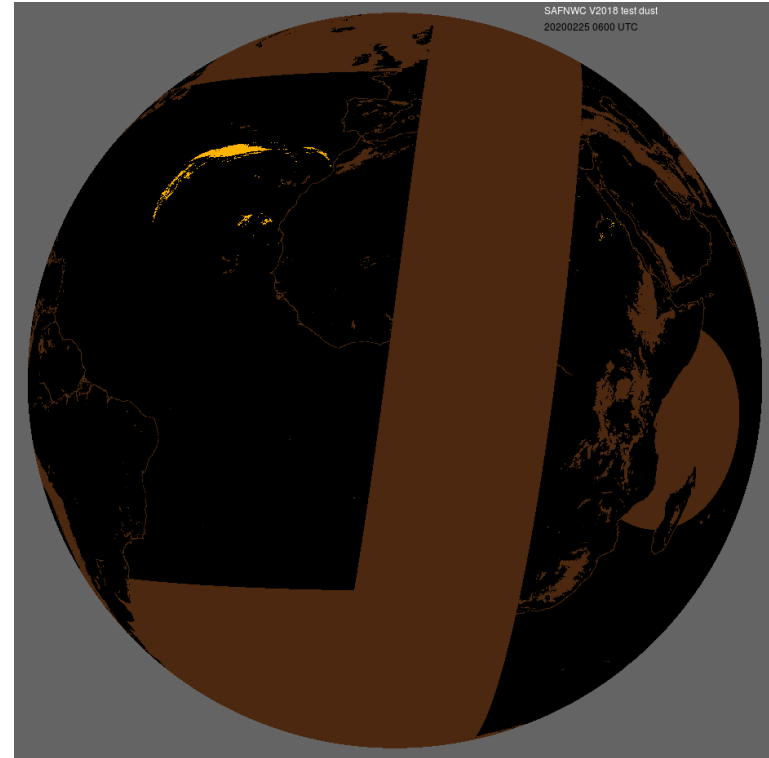


RGB dust

Preparation for MTG : new algorithm applied on Goes 16



Goes 16



By night over sea
20200225 at 06h00

MSG04



Conclusion

For MTG :

- the new algorithms have been improved especially by day over land**
- A Night algorithm over land has been created but detects very few cases compared to lidar observations**
- The new algorithms applied with Goes 16 and Himawari 8 channels present a good behaviour**
- This new version of dust flag will be available in the SAFNWC GEO software version delivered for MTG during 2022**